



# **2019 SkillsUSA Challenge Guide**

**Additive Manufacturing in  
Robotics on the  
Factory Floor**

# Challenge Overview

## Introduction

Additive manufacturing/3D printing is changing the way things are made. From the rapid prototyping lab all the way to the manufacturing floor. Companies in the automotive, aerospace and consumer goods industries are leaning into an era of Industry 4.0, a technological playing field where additive augments other technologies like robotics to provide higher throughput. Shave days off production cycles. Remove complexity from final assembly. Produce lightweight, high-strength structures. Compete in high-pace markets better. Thanks to the ability to easily add customization and design with complexity, the path to market can be quicker and more efficient today than ever before.

Traditional approaches to manufacturing are no longer the only way to bring your product to market. Additive manufacturing is rapid compared to traditional forms of manufacturing and this allows for multiple design iterations in which designs can be tested and improvements can be made immediately.



Image: Fanuc Robots & 3D Printed Manufacturing Aides Used on the Automotive Assembly Line

## Challenge Goal

The goal of this challenge is to demonstrate additive manufacturing skills by designing and fabricating and applying an end of arm tool (EOAT) in a simulated real-life manufacturing robotics scenario. By working with the design constraints of purpose, time, materials and a pre-programmed robotics program, participants will demonstrate their ability to conceptualize, design, iterate, and apply a 3D printed tool to a real-life manufacturing scenario.

Successful completion of the competition is defined as a well-documented, well-designed Tool that, aided by a Robot running a pre-installed Program, repeatably places an Emblem on a Target in the correct position and orientation.

## Challenge Background

Each competing team represents members manufacturing engineering group at an automotive manufacturer. As a manufacturing engineer working on a full-production sedan assembly line, you are responsible for improving the repeatability and speed of car assemblies.

The issue of placing the vehicle badge precisely onto the back bumper of the car has been brought up several times. This process involves operators manually picking up the manufacturer logo **emblem** from a supply **track** and then placing the emblem onto a **target** location on the vehicle body. It's been a complaint for years that this operation is a repetitive task that has a high rework rate (low repeatability) and low utilization (waste of operator time). During a recent process efficiency meeting, the automation of this emblem placement activity has been prioritized, and you have suggested that a **robot** with a 3D printed end-of-arm tool running a **program** that repeats for each panel to be treated may be right path forward.

## Challenge Description

To test a brilliant concept of the robotic emblem placement program, competing teams are using simulated **Components** of the automotive manufacturing environment:

- An **Emblem** that is approximately the same size and weight of the real-life emblem, but with magnets instead of adhesive.
- A **Track** that locates the Emblem in approximately the same place each time.
- A **Frame** made of 80/20 framing onto which the Target is permanently affixed
- A **Target** which is placed at the right height and location with respect to the Track.
- A **Robot** that will pick up the Emblem from the Track and place it on the Target.
- An **Adapter** that is permanently mounted to the Robot that provides mounting points for the end-of-arm Tool.
- A **Program** that the robot is running that can be triggered at any time to pick up an Emblem from the Track.
- **Rubber Bands** of which 2x may be used in the Tool design.

The teams' task in this competition is to take the provided Components (Emblem, Track, Target, Robot, and Program), and develop a **Tool** made of 3D printed parts and rubber bands that completes the automated concept.

# Component Kits

The competition components are located at the testing area and at desks for designing.

**Testing Area Component Kit (TACK)** is all equipment located at the actual competition testing location. Breaking components of the TACK will result in penalties as outlined in the scoring rubric. The TACK includes:

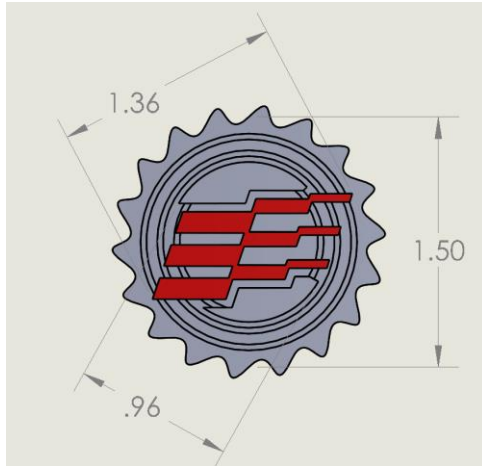
- 5x Emblems
- 1x Track
- 1x Target (on a platform)
- 1x Robot
- 2x Adapters (2x mounted onto the robot)
- 1x Program (running on the robot)
- 0x Rubber Bands (in Design Areas only)
- 0x USB Sticks

**Design Area Component Kit (DACK)** is all equipment provided to each team at the beginning of the competition. There is no penalty for breaking components of the DACK but it will be more difficult to test and design parts if DACK pieces are broken. The DACK includes:

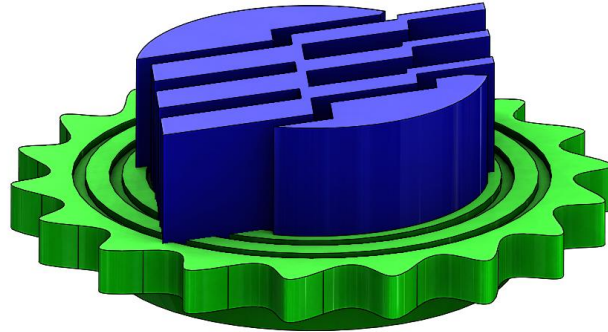
- 1x Emblem (magnet is removed)
- 0x Track
- 0x Target
- 0x Robot
- 1x Adapters (for design and Tool testing purposes)
- 0x Program (on Robot at TACK only)
- 2x Rubber Bands (extras will be provided until competition supply runs out).
- 1x USB Stick (provided by teams)

## Component Details: Emblem

The most important Component is the Emblem. The Emblem is the object to be picked up by the Robot running a pre-set Program and placed on the Target. The actual automotive emblems are applied with pressure-activated adhesives, but the simulated Emblem in the concept is a 3D printed plastic Emblem with the SkillsUSA logo on it with a magnet on the back.



Above: Various dimensions of the Emblem



Above (visual only): Blue = "Logo", Green = "Base"

### Description of the Component

- The **Emblem Base (highlighted green)** is the serrated disc and everything below it (including the magnet and tapered magnet holder). The Emblem Base has an approximate diameter of 1.5 inches, but at any point the diameter may be larger or smaller due to the teeth on the Base disc.
- The **Emblem Logo (highlighted blue)** is the clear and red components of the Emblem above the Base. The largest diameter of the base is 1.36 inches (across the SkillsUSA logo) and the smallest diameter is 0.96 inches (across the clear boss).

### Notes on Scoring

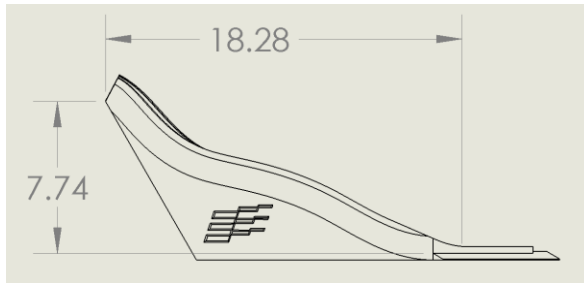
- Extra points are awarded for programs that avoid touching the Logo (on the physical object the clear and red regions) of the Emblem. See scoring guide for details.

### Kit Components

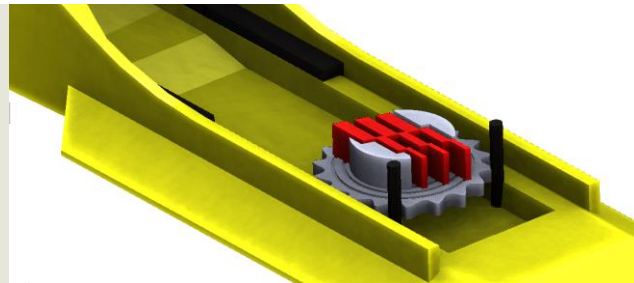
- There are 5x magnetic Emblems in each Testing Area Component Kit
  - As with all TACK Components, there is a penalty for breaking a TACK Emblem.
- There is 1x non-magnetic Emblems in each Design Area Component Kit.
  - As with all DACK Components, broken DACK Emblems will not be replaced.

## Component Details: Track

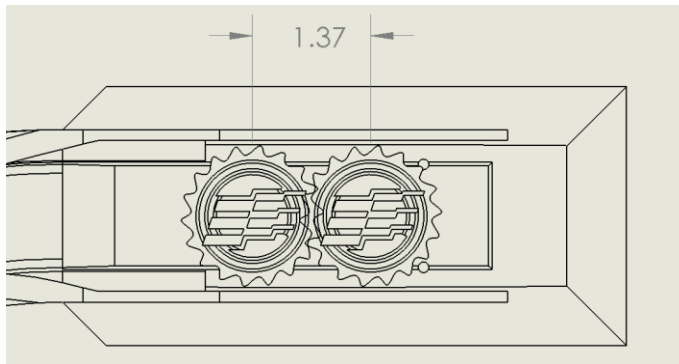
The Track is the Component that positions the Emblem before the Program is run. In the final installation of the robotic assembly, the track delivery system will be made from industrial framing and deliver the Emblem from another area of the production line. For the purposes of this concept and competition, the Track transports the Emblem a short distance to simulate the arrival of the Emblem for placement.



Above: The overall dimensions of the Track



Above: The rails and bumpers of the Track



Above: There is variability in the Emblem's final position.



Above: The Track is about 22 inches in total length.

### Description of the Component

- The Track transports the Emblem down a 22-inch-long track, descending about  $7\frac{3}{4}$  inches in height and moving the Emblem towards the robot by about  $18\frac{1}{4}$  inches.
- The Emblem descends the track on rails that touch the disc on the Emblem Base of the not the Logo or magnet boss.

### Notes on Scoring

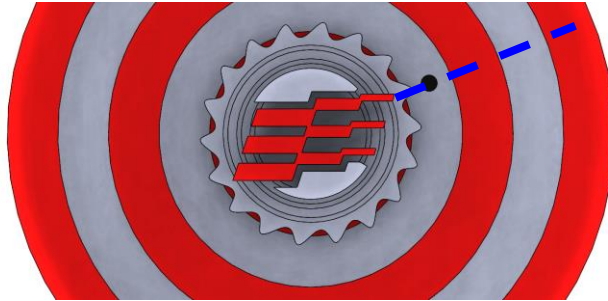
- When the Emblem has reached the bottom of the Track, it will be located somewhere between the end of the rails and the bumper pins (both shown in black above). This variance is approximately  $1\frac{3}{8}$  inches and the arm must account for this for repeatable success. See scoring guide for details.

### Kit Components

- Each TACK includes 1x Track
  - As with all TACK Components, there is a penalty for breaking a TACK Track.
- There are no Tracks in the DACK.

# Component Details: Target & Frame

The Target is the destination of the Emblem during the Robot Program. The Target does not ever move. In the center of the Emblem is a magnet that will attract the Emblem to simulate adhesive during the real robotics application.



Above: The Emblem shown is in the perfect Orientation.

## Description of the Component

- The Target has a magnet that will mate to the Emblem.
- The “tip” of the Emblem Logo will line up with a mark on the Target for full points.

## Notes on Scoring

- There are two important components to the score as it relates to the Target:
  - “Placement” is based on whether the Emblem ends up on the Target after the Robot’s Program has finished.
  - “Orientation” is measured in “teeth” is based on the number of Emblem teeth between the Target’s black Orientation indicator and the Emblem’s. The number of teeth will be rounded by the judge’s discretion.
    - Examples of judging rules below:



Orientation off by 1 Tooth



Orientation off by 2 Teeth



Orientation off by 0 Teeth



Orientation off by 7 Teeth

## Kit Components

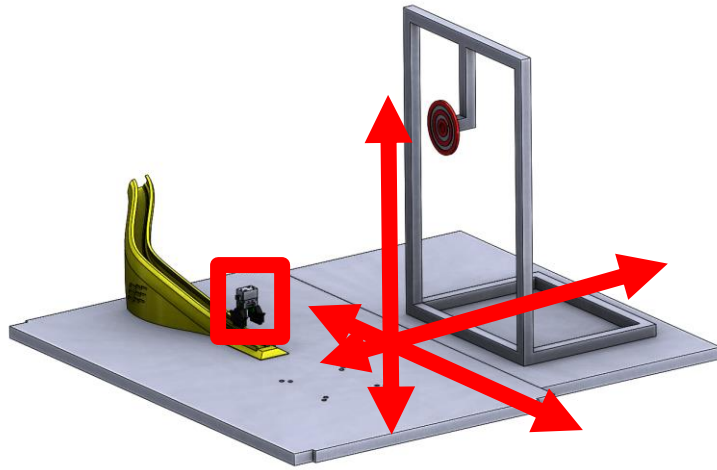
- Each TACK includes 1x Track
  - As with all TACK Components, there is a penalty for breaking a TACK Target.
- There are no Targets in the DACK.

# Component Details: Robot & Program

The Robot for this competition and concept demonstration is a Fanuc educational robot. The Program has been already created.



Above: The Fanuc robot used in this contest.



Above: XYZ definitions and grab position of the Robot

## Description of the Component .

- The Robot is at the XYZ location [0" 0" 0"] when it is in the "grab position" before closing.
- The Robot performs a close-range procedure just before moving to the [0" 0" 0"] grab position:
  - [-2.25" -1" 0.2"]
  - [-2.25" 0.2" 0.2"]
  - [0" 0" 3.5"]
  - [0" 0" 0"] "grab position"
- Note that the starting location of the Robot as well as the locations of the Track and Target are provided as a .STEP file in your DACK USB drive

## Notes on Scoring

- Note that it will be important to observe the Robot and take careful note of the above Program to ensure that the Robot does not crash into anything during the program.
  - If the Robot does crash during a program, it's likely that a TACK item or the team's Tool will break.

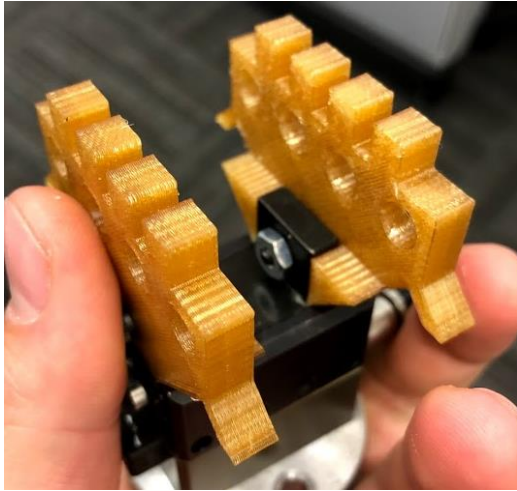
## Kit Components

- Each TACK includes 1x Robot running the Program
  - As with all TACK Components, there is a penalty for breaking a TACK Emblem.
- There are no Robots in the DACK.

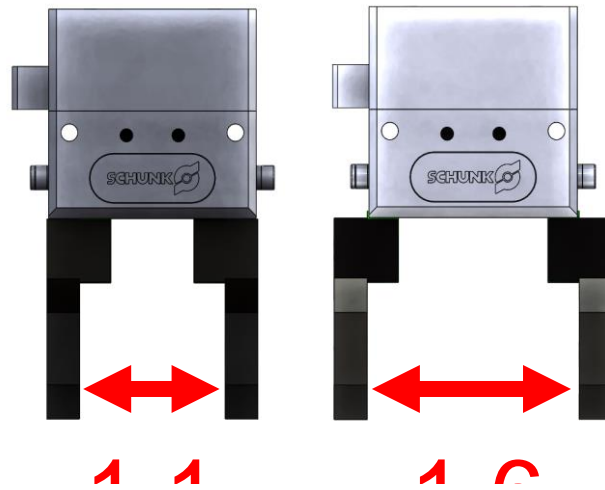


## Component Details: Adapter

The standard actuator attached to the Robot is a Schunk actuator that is permanently attached to 3D printed Adapters made out of Ultem 1010. The purpose of the Adapters is to provide various different connection points that teams may use to fix their Tool onto the Robot.



Above: The Adapters fit onto the Schunk actuator



Above: each Adapter moves 0.25 inches when closing.

### Description of the Component

- An Adapter fits onto each side
- The Adapters are provided at the TACK and each DACK includes 1x Adapter.
- If you believe that one of the TACK Adapters is worn or broken, alert competition staff immediately, as these are essential for fair play.

### Notes on Scoring

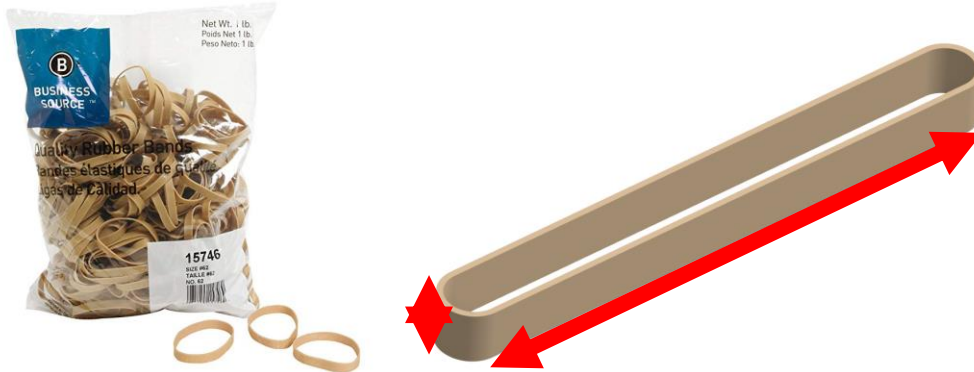
- The Tool may not affix to anything but the Adapter.
- The Tool may not harm or alter the Adapters (breaking TACK components will be met with a penalty).

### Kit Components

- Each TACK includes 2x Adapters
  - As with all TACK Components, there is a penalty for breaking a TACK Adapter.
- There will be 1x non-kitted Schunk actuator with Adapters fitted for experimentation and measurement to be shared by all teams. It will be located at one of the TACK locations.
- Each DACK includes 1x Adapter for measurement and fitting purposes.

## Component Details: Rubber Bands

Up to 2x complete, uncut Rubber Bands (provided) may be used in the final Tool.



Above: The rubber bands are size 62.

Above: Dimensions of a size 62 rubber band

### Description of the Component .

- Use of Rubber Bands must obey the following rules:
  - Rubber Bands may not affix to anything except the Tool or Adapter (not the Track, Target, Robot, etc.)
  - They may not be cut or broken (though they may be tied, including tied together)

### Kit Components

- Each DACK includes 2x Rubber Bands
  - Rubber Bands may be replaced (Up to 8x total per team) before supplies run out.
- There are no Rubber Bands at the TACK

## Component Details: USB Drive

Each team will receive the following files onto their USB drive at the beginning of the competition:

- **DACK\_Robot\_BEGIN\_Locations.STEP**
  - This STEP file has the geometry & relative positioning of the Track, Target, and BEGIN location of the Robot and Adapters
- **[COMPONENT].STEP (4x)**
  - A STEP file of the following Components: Ramp, Emblem, Adapter, Target
- **2019\_Challenge\_Guide.pdf**
  - A pdf of this challenge guide
- **2019\_Scoring\_Guide.pdf**
  - A pdf of the scoring guide

## Other Tool Requirements

Each team needs to carefully read through the Component Details above and observe the Robot Program carefully... there is a lot of room for creativity for solving the presented problem! However, each Tool must obey the following rules. Disobedience of these rules will lead to significant point penalties or disqualification of the Functional Testing portion of the score.

- **The Tool must have the Team Number legibly printed onto it**
  - This is a scored requirement that makes feasible 3D printing many Tools overnight (also mentioned in Print Deliverable Specifications below).
- **The Tool may only consist of 3D printed parts and Rubber Bands**
  - May consist of any part of Tuesday's print, Wednesday's print, and/or both.
- **The Tool may make use of only up to 2x Rubber Bands**
  - (See Component Details: Rubber Band)
- **The Tool may only affix to the Adapters provided**
  - (See Component Details: Adapter)
  - The Tool must remain attached to the Adapter(s) throughout the entire Program.

# Challenge Agenda

## Day 1, Tuesday

Tuesday is Day 1 of the competition. There will be 3.5 hours of design time available to contestants to design for their first of two opportunities to 3D print overnight. During the design time on Tuesday, the TACK (See Kit Descriptions) will be available for measurement and planning.

Reminders:

- Teams should document their journey in their engineering notebook (see judging rubric for details). This notebook may be taken home each night to finalize documentation.
- At the end of the design time, contestants must submit a file folder on their USB drive that matches the Print Deliverable Specifications specified below.

## Day 2, Wednesday

Wednesday is Day 2 of the competition. Students will receive their 3D printed parts from Tuesday's design efforts to test. Students will receive 3 more hours of design time; iterations will be 3D printed overnight. During the design time on Wednesday, the TACK will be available for part testing.

Reminders:

- Teams should document their journey in their engineering notebook (see judging rubric for details). This notebook may be taken home each night to finalize documentation.
- At the end of the design time, contestants must submit a file folder on their USB drive that matches the Print Deliverable Specifications specified below.

## Day 3, Thursday

Thursday is presentation day. At the end of the day on Wednesday, students were given their "judging time." Students are allowed to show up at the contest location 45 minutes prior to their judging time. Upon arrival, students will check in and receive their printed part from Wednesday. Students are allowed to inspect their Wednesday print and perform any sanding or assembly (as well as testing) desired before judging.

When the judges are ready (no sooner than the "judging time"), the team will be called to the presentation table, given 10 minutes to present their process, engineering notebook and printed designs. Judges will ask necessary questions to fully score student design before moving to the functional testing portion of judging. View the Judging Procedure below for details on the requirements of the presentation and judging. Students should fully review the Judging Rubric below to assist crafting their final presentation.

# Print Deliverable Specifications

On Tuesday and Wednesday, students will submit files to be 3D printed overnight (see agenda above). Below is the deliverable that must be submitted on your USB drive to have parts 3D printed.

## File Folder Specifications

- A file folder titled “Team [#] - [Day of Week] Submission” (fill in “[#]” with team number)
- Within the above folder, include the following files (**all** files must be formatted in this way: “Team [#] - [Day of Week] - [File Description]”):
  - a GrabCAD Print Project (.print) file saved at these settings:
    - Machine: F370
    - Slice Height: 0.010 inches
    - Material: ABS-M30
  - all STL (.stl) files of design (ensure correct mm/in scaling)
  - native CAD files of design
  - a Notepad text document (.txt) (not Word, .docx, etc.) document very clearly explaining the orientation of each part and infill style: sparse high density, sparse low density, or solid (this is because the administrators likely will need to rearrange files for actual printing).
    - To create a .txt file, in a folder Right-click > New > Text Document
    - Near the top of the .txt file include the estimated time for the .print file that was submitted.

## Design Specifications

- The Team Number must be legibly 3D printed into at least 1 component of each evening’s build.
- The total print must fit in a build envelope of 4.7”(L) x 4.7”(W) x 4.7”(H)
- Review rubric on material usage judging criteria
- The print must not exceed the time and material allowances referenced in the scoring guide. Parts that do not follow this requirement may not be printed overnight without notice. Double-check your .print file for resource consumption before submission each day.

# Judging Procedure

## Presentation

1. Prior to judging time, teams must ensure that their Tool is fully assembled and ready to attach to the Adapters. *Note: geometry-altering changes to Tools are not permitted between the presentation and functional testing.*
2. The team will give a 10-minute (no more) presentation on their design process. Leave time for Judges to ask questions.
  - a. Optional visual aids may include the following:
    - i. Powerpoint (or similar program) slides
    - ii. Your engineering notebook
    - iii. 3D printed parts printed **from Tuesday and Wednesday**
  - b. Review the rubric below to ensure that your Presentation & Engineering Notebook cover all judged points. (review rubric for Engineering Notebook criteria) Use your engineering notebook to demonstrate:
    - i. Design Process (How did you go about brainstorming and designing your parts? How did you effectively respond to Tuesday's print results during Wednesday's design time?)
    - ii. Team Functions, Roles and Responsibilities (How did you split up roles and take advantage of each other's strengths?)
    - iii. Limitations and Lessons Learned (Did anything go wrong during the past few days that was preventable? Where does your design fall short? What would you ask the patient if you had the opportunity?)

## Testing

3. Once the Presentation is over, the group will move to the TACK; the team will be given 30 seconds to attach their Tool to the Adapters.
  - a. Review the Tool Rules above for legal geometries and installation.
4. This testing procedure will be repeated 10 times:
  - a. The judge will place a random into the Track (not forcefully).
    - i. There may be no preference of particular Emblems or Tracks for use during Functional Testing
  - b. If the Emblem falls out of the Track or out of alignment (see the legal range of position in Component Details: Track), then the Judge will begin again with a new Emblem.
  - c. Once the Emblem is motionless at the base of the Track, the judge will initiate the Program.
  - d. Based on the result of the Program, points will be awarded for Placement and Orientation (see details in Rubric and Component Details: Target).'
  - e. You will be allowed to "adjust" the placement of your Tool up to 3 times at a point penalty throughout the 10 testing runs.

# 2019 SkillsUSA Mini Challenge Guide

The “Mini Challenge” is a short activity that tests a different area of competitors’ knowledge of additive manufacturing. This year, the focus is the “*Economics of Additive Manufacturing.*” How well do you understand 3D printing and economies of scale?

## Procedure and Rules

1. Read the scenario and questions below. Competitors will have 60 minutes to complete the Mini Challenge.
2. Fulfill the deliverable as described in Deliverable Instructions (you’ll need the separate Scheduling Sheet for your deliverable).

## Background: Incoming Requests

You work at a technology company called SixStar as an FDM lab technician. Although there are internal departments at SixStar that use your 3D printing services, a large part of your lab’s activity is doing paid services for outside organizations.

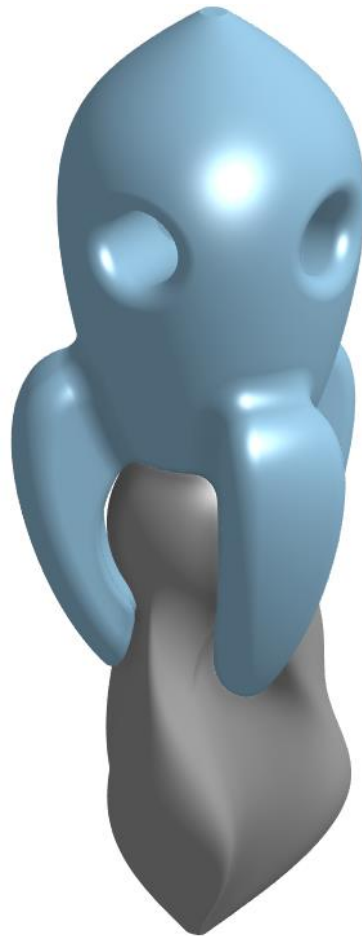
On this particular Monday, you’re in early on at 4:15am to get the shop prepared for the rest of your staff to arrive at 6:00am. This should be a quiet week because all your printers are running with important jobs (and will be running all week non-stop) except a Stratasys F370 which is sitting idle.

All of a sudden, at 5:00am exactly, three urgent requests come in from outside companies. All three are well-respected clients (LunarTech, FabricaTech, and SoarTech), and they all seem to have urgent, expensive projects to finish by 5pm on Friday!

...that’s always how it happens on Mondays...

## Background: LunarTech Request

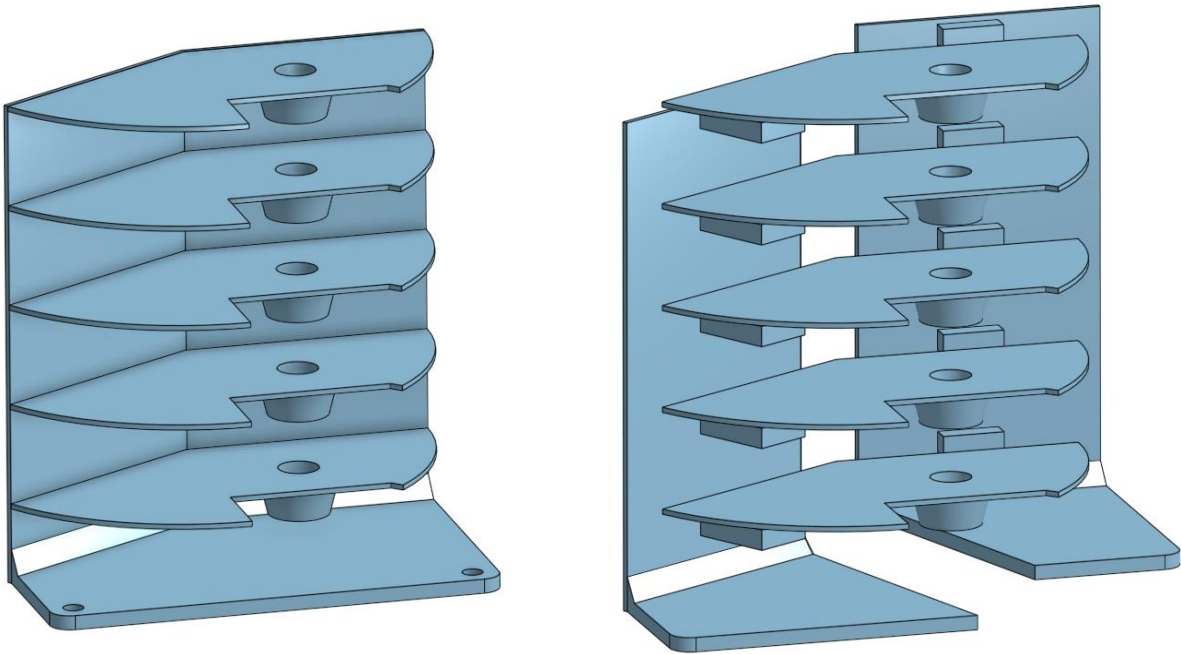
- Customer: LunarTech
- Part Name: CartoonRocketv2.step
- Material: ASA
- Layer Height: See instructions
- Needed Quantity: 2
- Print instructions: “SixStar Lab, it’s Jason at LunarTech up the highway! Super urgent, need to come pick this up by 5pm Friday... it’s a cosmetic part so it doesn’t need to be strong at all, but the better the resolution of the print, the more I’m willing to pay since it will need less sanding on our end! If you can print it high-resolution, I’ll pay \$3000; for medium res I’ll pay \$1500, and for low-res I’ll pay \$500.”





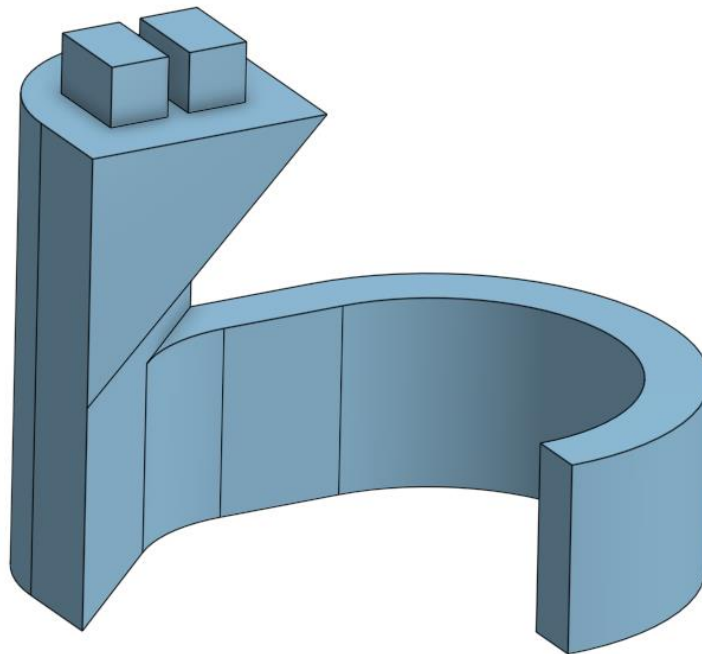
## Background: FabricaTech Request

- Customer: FabricaTech
- Part Name: PN55Fixture.step
- Material: ASA
- Layer Height: 0.013”
- Needed Quantity: 2
- Print instructions: “Hey SixStar team, this is Joan from FabricaTech Operations in downtown. Remember how we talked about those 3D printed robotic staging shelf? I got last-minute approval yesterday to print those for a line pilot next week. I remember you mentioned that they will print faster when printed in multiple pieces... but it’s going to cost me something to assemble, so I’d rather have it together. I really need of them by end-of-day Friday...5pm if you can. I’m willing to pay \$3000 if you print it assembled and \$1500 if it’s unassembled.”



## Background: SoarTech Request

- Customer: SoarTech
- Part Name: 3967-03-02AngleLink.step
- Material: ASA
- Layer Height: 0.010”
- Quantity: at least 200
- Print instructions: “SixStar, this is SoarTech down the street... we just got a HUGE order for our Link3967 systems... I’ll need 4,000 of these angle links ready by Friday at noon for pickup. I know you can’t make them all... but I need (NEEEEEED) at least 200! We’ve dialed in the settings: ASA 0.010” solid, so please just print as many as you can! Willing to pay \$20/pop since it’s urgent.”



# Background: Organizing the Data

As the machines of your shop whirl and churn on parts, you take a sip of your coffee and stare at the lone F370.

It's now 5:15am.

You're nervous, because the three customers (LunarTech, FabricaTech, and LinkTech) are all important customers... not fulfilling any of their orders completely will probably damage SixStar's relationship with that customer.

You guess that not completely fulfilling any of the orders will probably lose you 5% of that company's business for the next year. You thumb through last year's books, looking for the revenue from each of these businesses:

- LunarTech: \$30,000
  - So 5% lost sales = **-\$1,500**
- FabricaTech: \$20,000
  - So 5% lost sales = **-\$1,000**
- SoarTech: \$10,000
  - So 5% lost sales = **-\$500**

After thinking things through, you decide there are a few different "Options" that you can print to fulfill these orders. Each Option satisfies By running through the Print Instructions, you come up with the following Options chart.

	Option Code	Quantity in Option	Revenue	Settings (ASA)	Time (hours)	Tray Space Needed
<b>LunarTech</b> Quantity: 2 Penalty: \$1,500	L1 ("high-res")	1	\$3,000	0.007"	18	1/2
	L2 ("mid-res")	1	\$1,500	0.010"	12	1/2
	L3 ("low-res")	1	\$500	0.013"	6	1/2
<b>FabricaTech</b> Quantity: 2 Penalty: \$1,000	F1 ("assembled")	1	\$3,000	0.013"	24	1/2
	F2 ("disassembled")	1	\$1,500	0.013"	12	1
<b>SoarTech</b> Quantity: at least 200 Penalty: \$500	S1 ("quarter-tray")	50	\$1,000	0.010"	6	1/4
	S2 ("half-tray")	125	\$2,500	0.010"	12	1/2
	S3 ("full tray")	200	\$4,000	0.010"	24	1

Figure MC-1

# The Challenge

It's now 5:30am. You've got 30 minutes until your staff come in and you put your plan into action.

You drain the rest of your coffee.

It's now up to you to design a number of Builds that the F370 will run throughout the week. Each Build will consist of 1 or more Options from Figure MC-1. The Builds must be scheduled in the Scheduling Sheet separate from this guide.

## Build Creation Rules

- **Build Size:** Each Build may not consist of Options that require more than 1 full Tray (see Tray Space Needed column in MC-1).
  - **Summing Times:** The time required for two different options is approximated to be simply the sum of the Options' times. (Example: time required for F1 + S1 = 30 hours)
- **Matching Settings:** Options within a single Build must have matching Settings (See Settings column in MC-1)
- **Scheduling:** Lab staff is only available 6am - 2pm each day to remove a Build and start another one.
  - **Instant Changeovers:** For the purposes of scheduling, there are zero (0) hours required in between Builds (even if changing layer height Settings).
- **Support Removal:** Every item in all Options requires at least 8 hours for support removal and packaging. *Therefore, any parts that aren't finished at least 8 hours before 5pm Friday will not be delivered.*

## Deliverable Instructions

Fill out a Scheduling Sheet (Separate from this Mini Challenge Guide). Turn the Scheduling Sheet in at the end of the allowed time. **No late submissions.**

## Scoring Rubric

\_\_\_/20 points - None of the Build size, settings, or scheduling rules (in section Build Creation Rules) were violated.

\_\_\_/80 points - Net Revenue generation from Scheduling Sheet

- 80/80: \$14,500 or higher
- 60/80: \$13,500 to \$14,499
- 40/80: \$10,000 to \$13,499
- 0/80: under \$10,000

